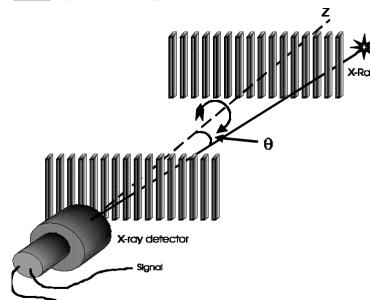
# Find the thermal energy of a solar flare (e.g. 06-Jan-04 7:30)

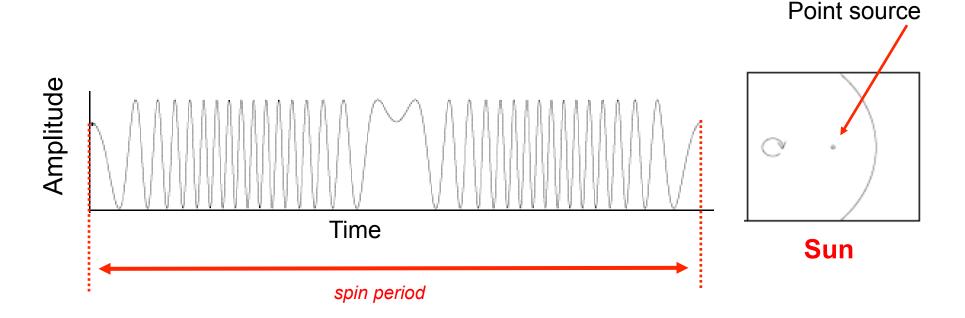


# **Rotating Modulating Collimators**

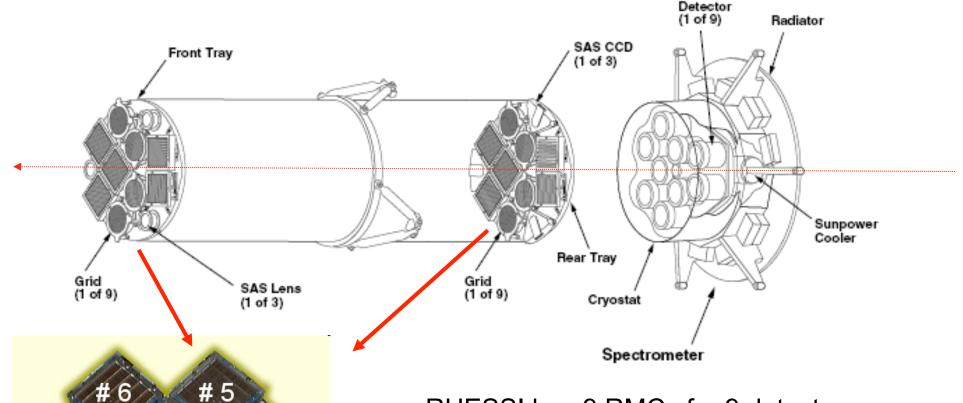


RHESSI detectors look at the source through a pair of grids called Rotating Modulating Collimator (RMC)

Spacecraft spins about once every ~4 sec => artificial modulation of incoming X-ray flux



# RHESSI imaging



RHESSI has 9 RMCs for 9 detectors

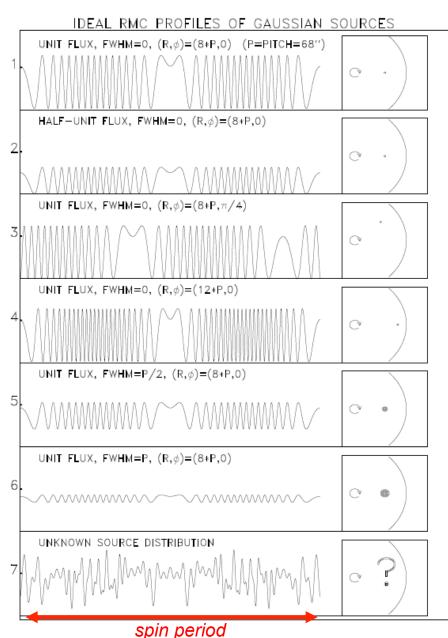
Slats/Slits spacing growing with detector (RMC) number

P angular resolution from ~2.3" (RMC #1) to 180" (RMC #9)

Germanium



# RHESSI: ideal modulated lightcurves



Modulation profiles for various ideal sources for a grid of pitch **P** with equal slits and slats

Point source

Half flux from the point source => note half amplitude

45 degrees angle => note change of phase

Source further from the axis => note change of modulation frequency

Source size=P/2 => note change of the amplitude

Source size=P => note change of modulation depth (no modulation for source size >> P)

Modulation encodes spatial source information:

Phase of the modulation => position angle

Distance from the centre => modulation frequency

Amplitude => source size



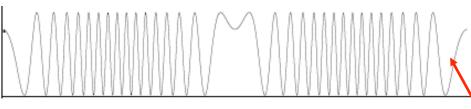
# Modulated lightcurves

# Sun Point source

Incoming **photon flux** from **pixel m** of the source

**Time interval =**observation time – dead time

**Detector area** 



 $C_i = A \sum_m P_{im} F_m \Delta t_i.$ 

Modulated Lightcurve

Probability to find a photon from *m-th pixel* in *i-th time* bin (basically the response of the instrument)

To find an image is to find the solution:

$$I_m = \frac{1}{A} \sum_{i=1}^{N} [C_i / \Delta t_i] \widehat{P}_{im},$$

Photons (counts) in i-th time bin



The fundamental problem of RHESSI imaging is to find the spatial photon distribution knowing the modulated time profile or *visibilities* (solve an inverse problem!;():

$$I_m = \frac{1}{A} \sum_{i=1}^{N} [C_i / \Delta t_i] \widehat{P}_{im},$$

To accomplish this task various imaging algorithms to solve this inverse problem exist:

Back Projection
CLEAN
Maximum Entropy Method MEM based (e.g. MEM NJIT)
PIXON
Forward Fit
Interpolated (smooth) FFT



You method could be here!



# RHESSI imaging: Back Projection

**Back projection** (Mertz, Nakano, and Kilner, 1986) is the most basic method of image reconstruction (roughly 2D Fourier transforms(Kilner and Nakano, 1989)), leads to so-called 'dirty map' or 'dirty image'.

$$I_m = \frac{1}{A} \sum_{i=1}^{N} [\mathbf{c}_i / \Delta t_i] \widehat{P}_{im},$$

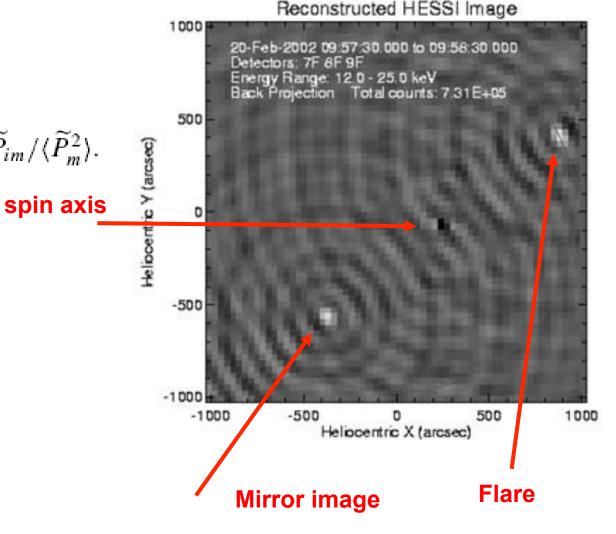
$$\widetilde{P}_{im} = P_{im} - \langle P_m \rangle$$
  $\widehat{P}_{im} = \widetilde{P}_{im} / \langle \widetilde{P}_m^2 \rangle$ .

### Advantages:

- Very fast
- Linear and simple

### **Disadvantages:**

- poor quality images
- no reliable source sizes





# RHESSI imaging: CLEAN

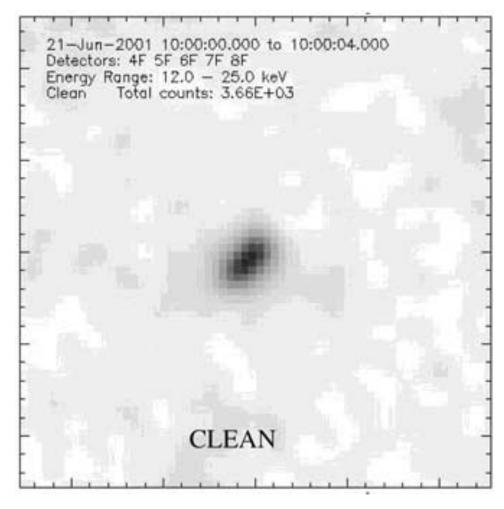
Clean assumes that the image is a superposition of point sources convolved with Point Spread Function (PSF) and iteratively cleans the initial back-projected image until either negative residuals or max number of iterations Högbom (1974).

### Advantages:

- Relatively fast
- Positive fluxes

### Disadvantages:

- Nonlinear
- Overestimates source sizes
- Likely to misinterpret extended sources



# RHESSI imaging: MEM

Maximum Entropy Methods (MEM) algorithm looks for the map that is both consistent with the data and contains the least information about the source (i.e. maximum

entropy). (Hurford et al, 2002)

$$\chi^2 = \sum_i \frac{(\mathcal{C}_i - \mathcal{E}_i)^2}{\sigma_i^2}, \quad \mathcal{H} = -\sum_m F_m \log F_m,$$

consistency with data

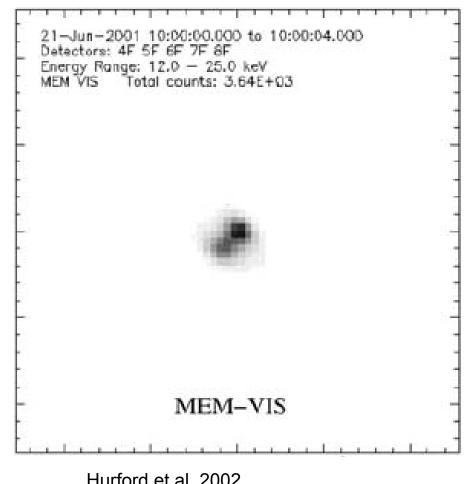
Maximising entropy

### Advantages:

- Relatively fast
- Positive fluxes

### **Disadvantages:**

- Nonlinear
- Underestimates source sizes



Hurford et al. 2002



# RHESSI imaging: Forward Fitting

Forward Fit assumes that the source can be presented as a prescribed functional form with a number of free parameters (for example, two circular Gaussian sources) and looks for the parameters which produce a map that is consistent with the data.

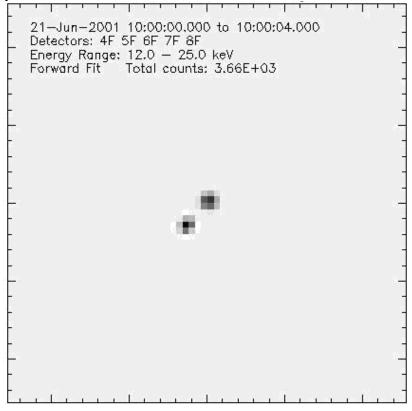
(Aschwanden et al, 2002; Hurford et al, 2002)

### **Advantages:**

- Fast
- Positive fluxes
- Source sizes and errors on parameters

### **Disadvantages:**

Does not work well for complex sources





# RHESSI imaging: PIXON

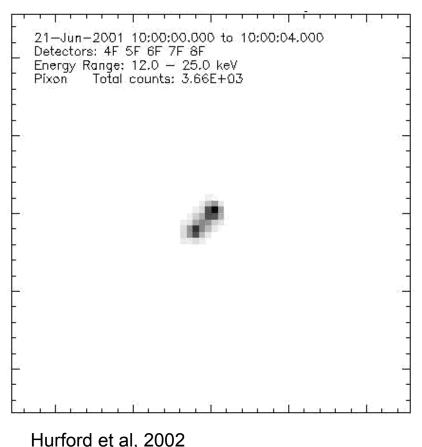
Pixon looks for the simplest model for the image that is consistent with the data (suitable CHI2) (Puetter, 1995; Metcalf et al., 1996). Pixon simultaneously minimises smoothes the image locally (minimisation of independent patches) and simultaneously consistent with the data.

### Advantages:

- Photometric accuracy
- no spurious features

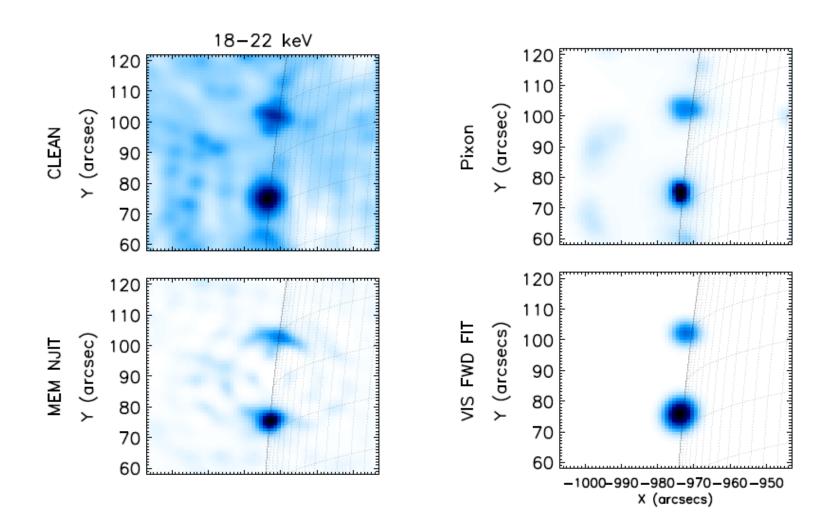
### **Disadvantages:**

- Very slow (too orders of magnitude)





# Comparing imaging algorithms





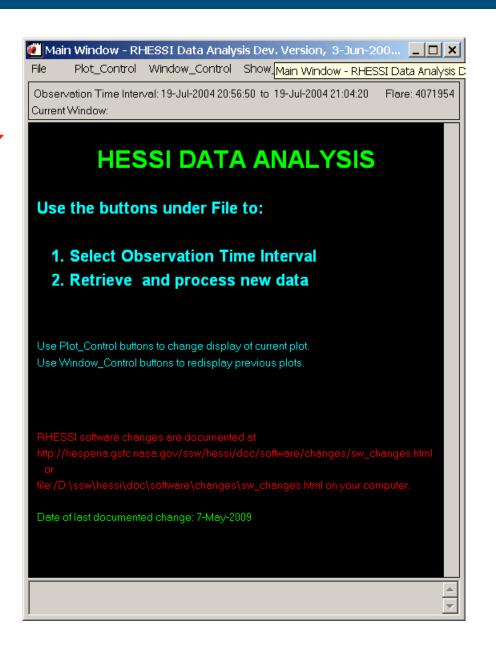
# RHESSI imaging

1) Start GUI interface

IDL>hessi

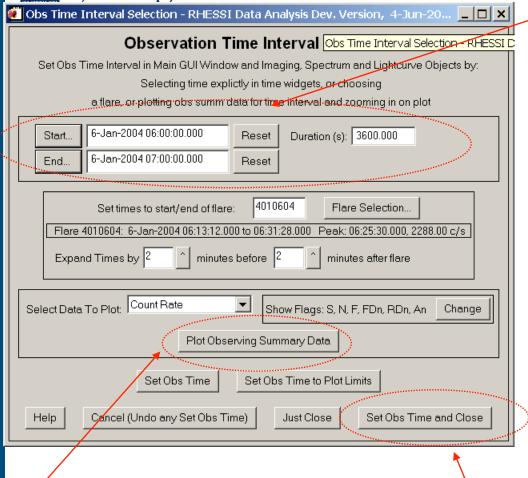
- 2) You will see this
- 3) Let us select a flare

January 06, 2004 ~06:20 UT





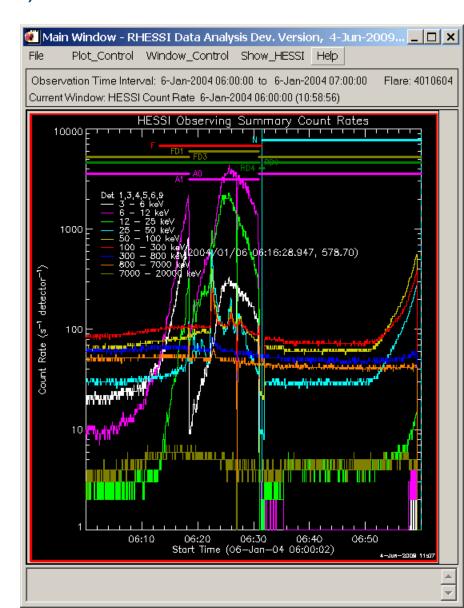
# Observing summary data



2) Plot observing summary data

3) Set obs time & close

### 1) Select time interval

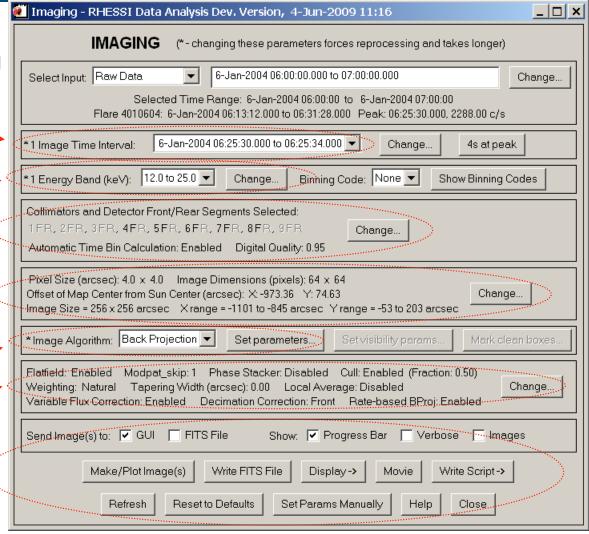




# RHESSI imaging

In the mane window select File ->Retrieve/Process data-> Imaging

- 1) Select time interval
- 2) Select energy range
- 3) Select detectors
- 4) Select image details: size, pixel size, xy offset
- 5) Select image algorithm
- 6) Do not mess with this (unless you know what you are doing)
- 7) Choose output





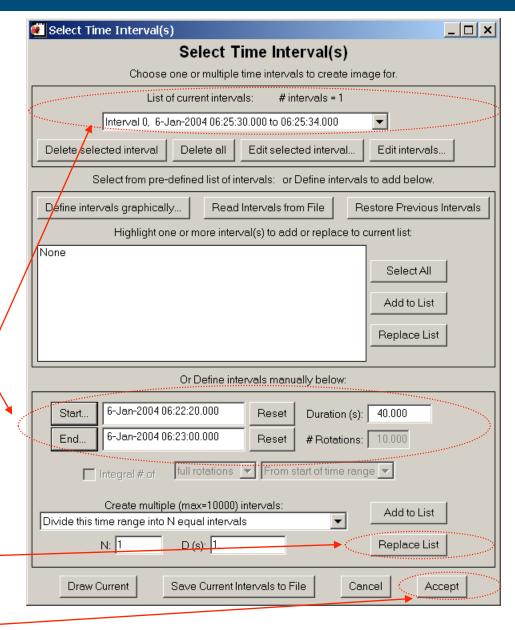
# Imaging time interval

## Selecting time interval....

1) Define time interval here

### **Good practice:**

- a) Time interval is a multiple of spin period (or a half)
- b) The weaker the flare the longer the time (20-40 seconds => good images for a medium class flare)
- 2) Always press replace list (note the change at the top)
- 3) Press accept





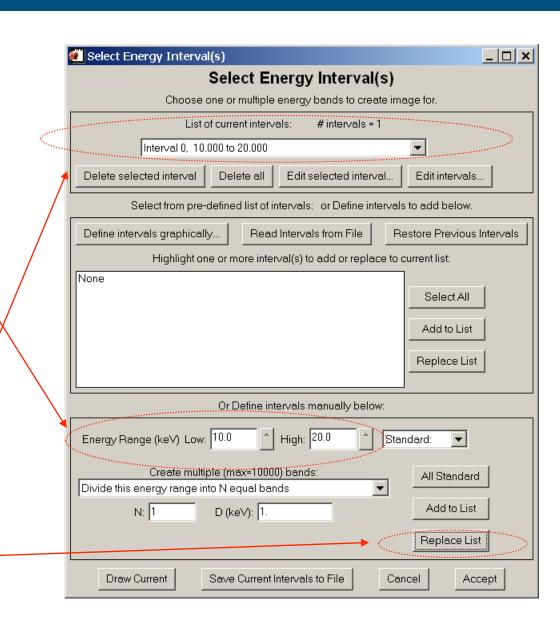
# Imaging energy range

### Selecting energy interval....

1) Define energy range here

### **Good practice:**

- a) Time interval is more than a few keV
- b) The weaker the flare the longer the energy range (5-20 of keV is OK)
- c) The higher the energy the longer the energy range (recall X-ray spectrum) (~100 of keV at 200 keV)
- 2) Always press replace list (note the change at the top)
  - 3) Press accept



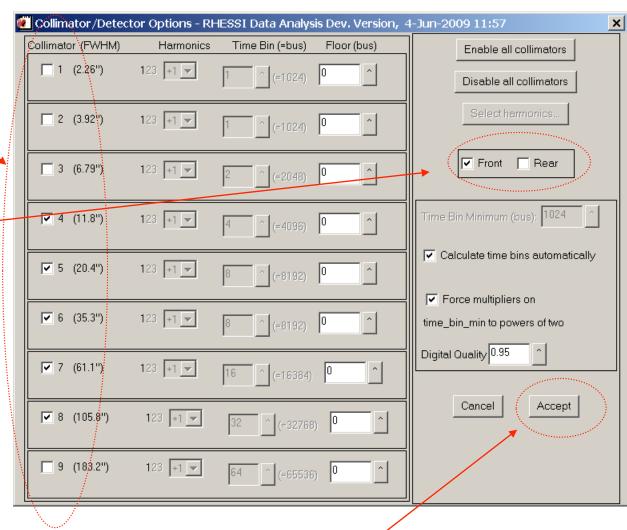


### **Selecting Collimators/Detectors ...**

1) Define RMC here

### **Good practice:**

- a) Front for energies~300keV, Rear for higherenergies (Det#1 up to 100 keV)
- b) Det #3-8 is a common choice
- c) Det#2 above 20-25 keV only
- d) Det#9 for scales >~180"



2) Press accept

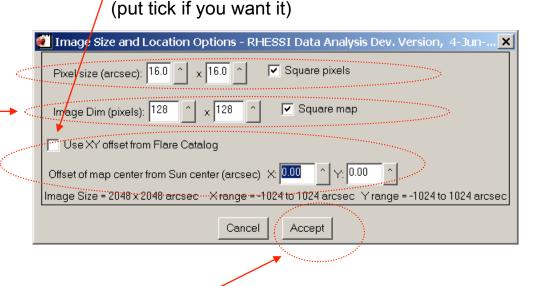


# **Selecting Collimators/Detectors ...**

- 1) Define pixel size ——
- 2) Define image size
- 3) Set the centre of the image as offset from the Sun centre

### **Good practice:**

- a) Pixel size less than RMC FWHM
- b) Use small image size ~64x64 or 32x32 (especially with Pixon)
- c) Keep in mind where the spin axis is



It is not bad idea to use XYoffset from flare catalog

4) As usual press 'accept' when finished

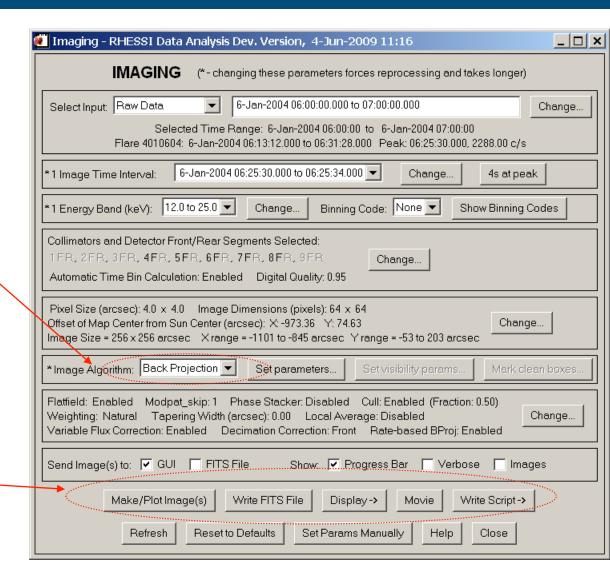


# RHESSI imaging

### Finally ...

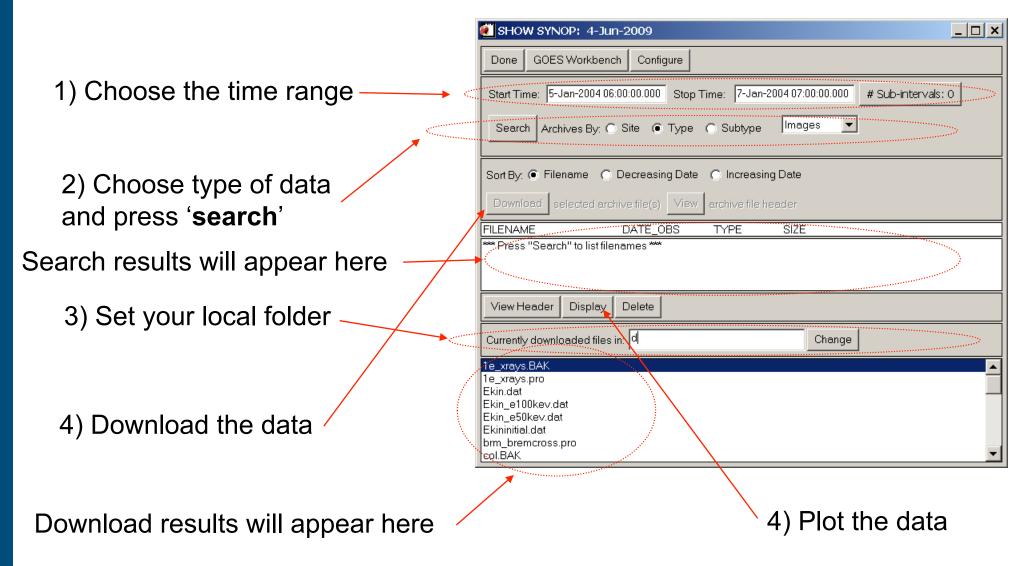
1) Choose algorithm

2) Output type (save as image as a file or display in the main window)





### Use synoptic data ... (almost all main solar data are accessible !!!)





# Making an image from command line

```
<= Defining imaging object anything instead of 'obj'
obj = hsi image()
obj-> set, det_index_mask= [0, 0, 1, 1, 1, 1, 1, 1, 0] <= Detectors used #3-8
obj-> set, im energy binning= [10.0, 20.0] <= Energy range used from 10 to 20 keV
obj-> set, im_time_interval= '6-Jan-2004 '+['06:22:20', '06:23:00'] <= time interval
obj-> set, image algorithm= 'Back Projection' <= image algoritm; could be Clean, Pixon, etc
obj-> set, image_dim= [128, 128]
                                      <= image size in pixels
obj-> set, pixel_size= [32., 32.]
                                      <= pixel size in arcseconds
obj-> set, use_flare_xyoffset= 0
                                    <= if set to 1 uses catalog data, if set to 0 not
obj-> set, xyoffset= [0.0, 0.0]
                                    <= sets image centre coordinates
data = obj-> getdata() ; retrieve the last image made
obj-> plot ; plot the last image
obj-> plotman
                      ; plot the last image in plotman
```



# Visibilities forward fit 1

```
obj = hsi image()
obj-> set, det index mask= [0, 1, 1, 1, 1, 1, 1, 0, 0]
obj-> set, im_time_interval= '6-Jan-2004 '+['06:22:20', '06:23:00']
obj-> set, im_energy_binning=[25.,35.]
obj-> set, image algorithm= 'VIS FWDFIT'
                                                  <=visibilities forward fit to be used
obj-> set, xyoffset=[-970,73]
                                                   <= centre of the map
obj-> set, use_phz_stacker= 1
                                            <= stacking into roll bins
;obj-> set,PHZ_radius=10.
                                      <= automatic choice of roll bins based on the characteristic scale 10"</p>
obj-> set,image_dim=[64,64]
obj-> set,pixel size=[1.0,1.0]
obj-> set, vf_ multi=1
                                           <= two sources
obj-> set,phz n roll bins control=[20,38,20,20,12,12,12,12,20]
                                                                       <= manual choice of roll bins
;sets the number of roll bins per detector
; useful controls when calculating the visibilities
obj-> set, vis edit=1, vis combine=1
; remove outliers and combine conjugates
```



# Visibilities Forward Fit 2

```
our_fit=obj ->get(/vf_srcout)
                                                           <= gets parameters out of object
gets visibilities parameters
                                                   <= errors on the fit parameters
fit_err=obj ->get(/vf_sigma)
gets visibilities parameter errors
you can set some initial parameters for you visibility structure
our fit.srctype=['ellipse', 'ellipse']
                                              <= two ellipse fit
our_fit.srcflux=[11,9] <= fluxes per ellipse
our_fit.srcfwhm=[7,6] <=FWHMs of the sources
                                                                       <= two source sizes per
our_fit.eccen=[0.7,0.7]
                                 <= ellipse eccentricities
our_fit.srcpa=[175,-178]
                                     <= position anlgles
our fit.srcx=[907,904]
                                <= x coordinates of the ellipse/circle centre
our fit.srcy=[248,272]
                              <= y coordinates of the ellipse/circle centre
obj -> set, vf srcin=our fit
                                    <= setting parameters as initial guess for forward fit
; sets out fit params
obj-> plot
                               <= plotting the output map (image)
obj->plotman
```



# Instead of conclusions: useful URLs

These lecture notes and example IDL scripts:

http://www.astro.gla.ac.uk/users/eduard/sodas

RHESSI imaging overview (good collection):

http://hesperia.gsfc.nasa.gov/hessi/instrumentation.htm

RHESSI imaging tutorials (from first steps to advanced level ): http://hesperia.gsfc.nasa.gov/rhessidatacenter/imaging/overview.html

Description of all RHESSI imaging software parameters: http://hesperia.gsfc.nasa.gov/ssw/hessi/doc/hsi\_params\_all.htm